



1002HL Hexscreen Electric Thruster with 14600XLR Motor Performance Table

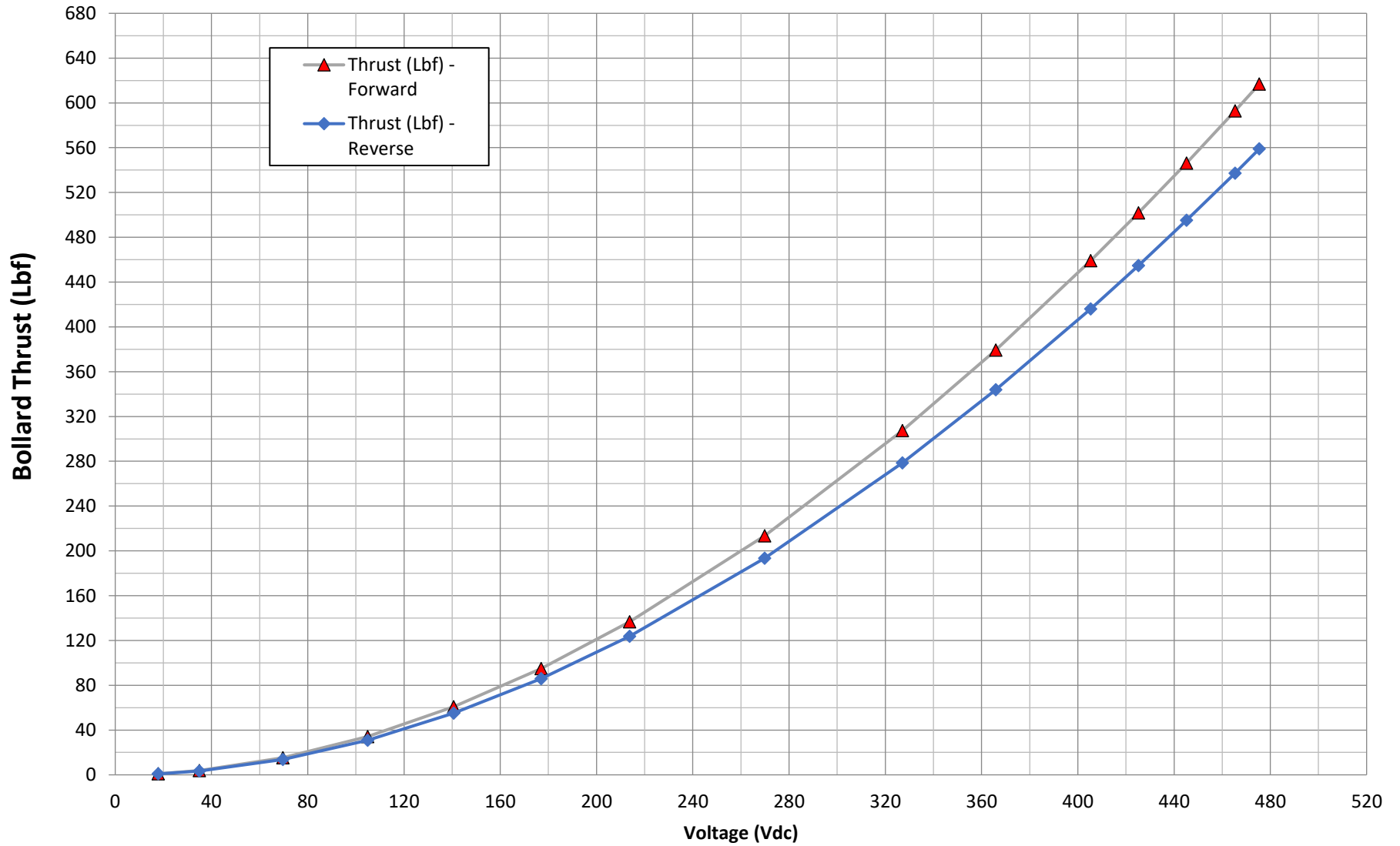
Speed (RPM)	System Voltage (VDC)	Min Voltage (VDC)	Current (A rms)	Bollard Thrust		Reverse Thrust		Power Shaft		Power In		Efficiency (Pout/Pin)
				0 (Lbf)	0 (Kgf)	(Lbf)	(Kgf)	(HP)	(Watts)	(Watts)	(HP)	
100	600	17.8	0.6	1	0.4	1	0.4	0.02	13	13	0.0	97.0%
200	600	35.0	0.8	4	1.7	3	1.6	0.04	31	32	0.0	98.1%
400	600	69.7	1.4	15	6.9	14	6.2	0.14	108	110	0.1	98.4%
600	600	104.9	2.3	34	15.5	31	14.0	0.37	275	280	0.4	98.2%
800	600	140.7	3.7	61	27.5	55	25.0	0.78	579	591	0.8	97.8%
1000	600	176.9	5.4	95	43.0	86	39.0	1.43	1064	1091	1.5	97.5%
1200	600	213.7	7.5	137	62.0	124	56.1	2.38	1775	1829	2.5	97.1%
1500	600	269.8	11.4	213	96.8	193	87.7	4.51	3368	3491	4.7	96.5%
1800	600	327.1	16.1	307	139.4	279	126.3	7.68	5726	5973	8.0	95.9%
2000	600	366.0	19.7	379	172.1	344	156.0	10.45	7798	8170	11.0	95.5%
2200	600	405.3	23.8	459	208.2	416	188.7	13.84	10325	10863	14.6	95.0%
2300	600	425.2	25.9	502	227.6	455	206.3	15.78	11773	12413	16.6	94.8%
2400	600	445.2	28.2	546	247.8	495	224.6	17.90	13351	14106	18.9	94.6%
2500	600	465.3	30.5	593	268.9	537	243.7	20.19	15065	15952	21.4	94.4%
2550	600	475.4	31.7	617	279.8	559	253.5	21.41	15975	16933	22.7	94.3%

Table Information:

- 1) The Minimum Voltage column in the above table shows the minimum Voltage needed to achieve the performance at that corresponding propeller RPM/Thrust.
- 2) The Current shown represents the continues RMS Current to the motor to achieve the Thrust at the corresponding propeller RPM.
- 3) The Shaft HP developed is a function of the propeller and increases with propeller RPM.
- 4) The maximum performance achieved will depend on the limitations of customers system Voltage and driver Current capacity.
- 5) For Thrust at Forward Vehicle Speed (Kts), anything lower than 500 RPM varies greatly with vehicle design.
- 6) The Current/RPM might need to be limited depending on customer connector spec and or system Current limitations.
- 7) Minimum Voltage to achieve full Thrust is 475 VDC.
- 8) Max Voltage should not exceed 10% of rated Voltage.



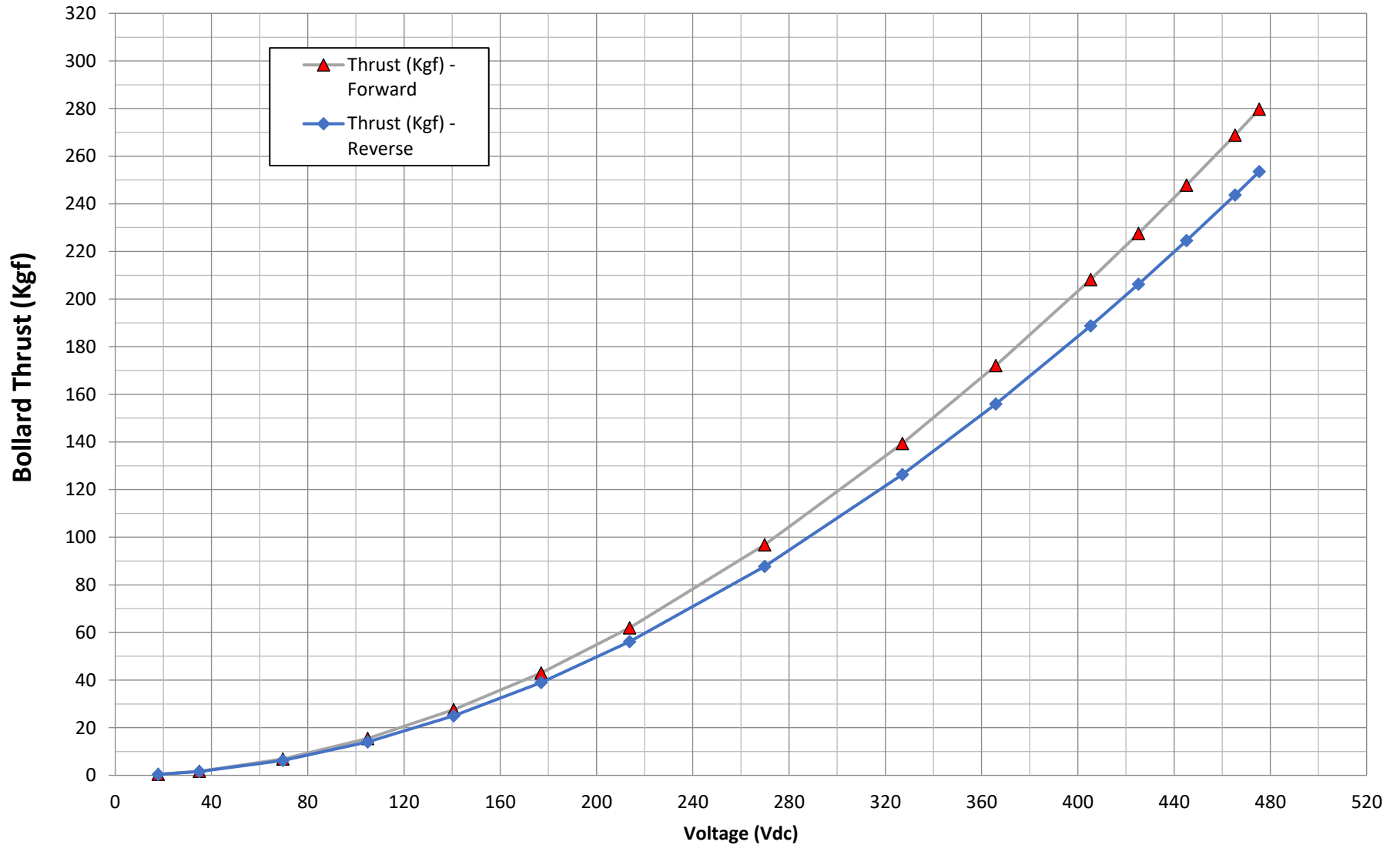
1002HL-14600XLR Hexscreen Electric Thruster Thrust (Lbf) vs Voltage (Vdc)



Note:
System Voltage equals 600VDC. Graph shows Thrust with Voltages below 600VDC.



1002HL-14600XLR Hexscreen Electric Thruster Thrust (Kgf) vs Voltage (Vdc)

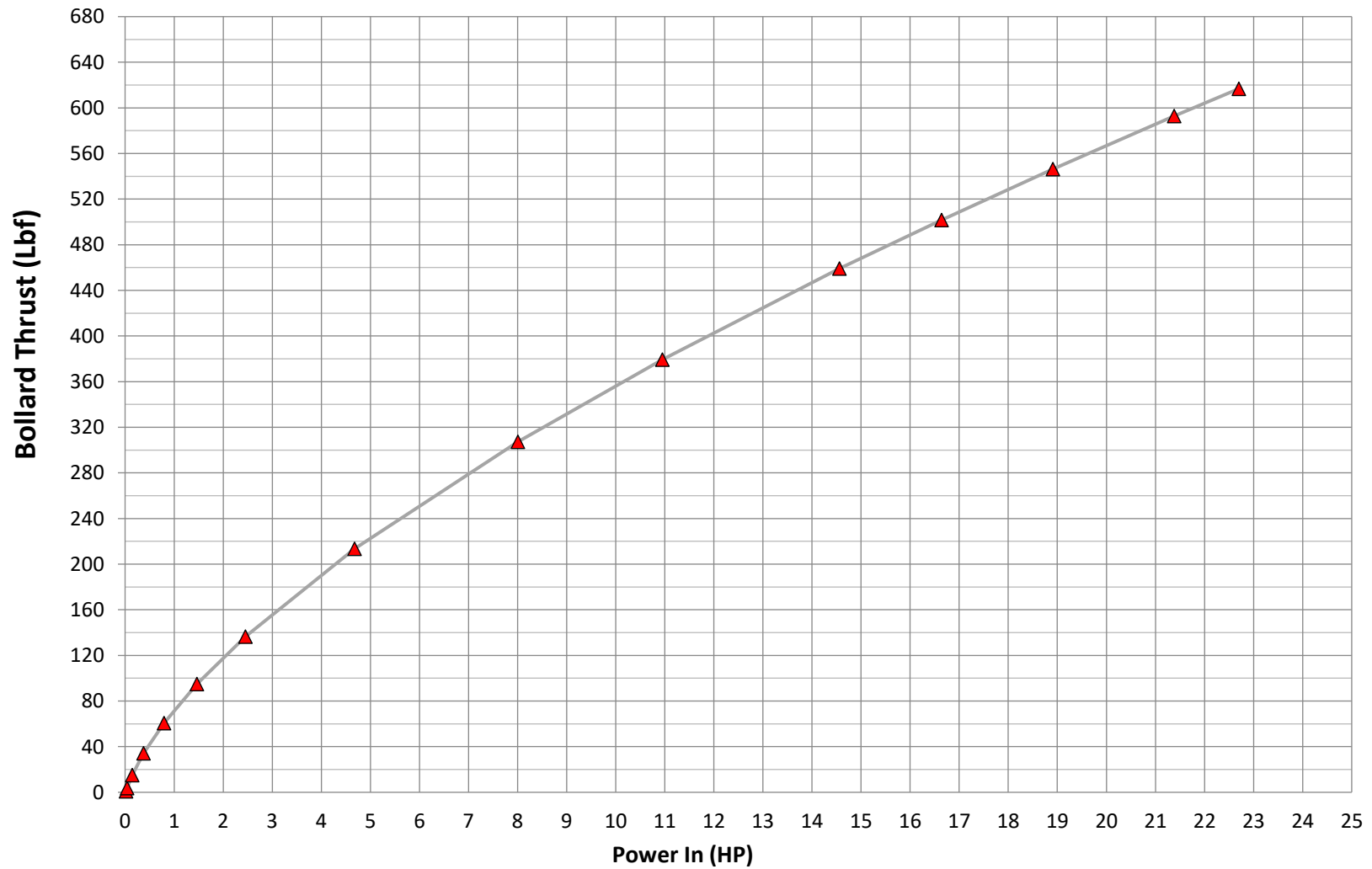


Note:
System Voltage equals 600VDC. Graph shows Thrust with Voltages below 600VDC.



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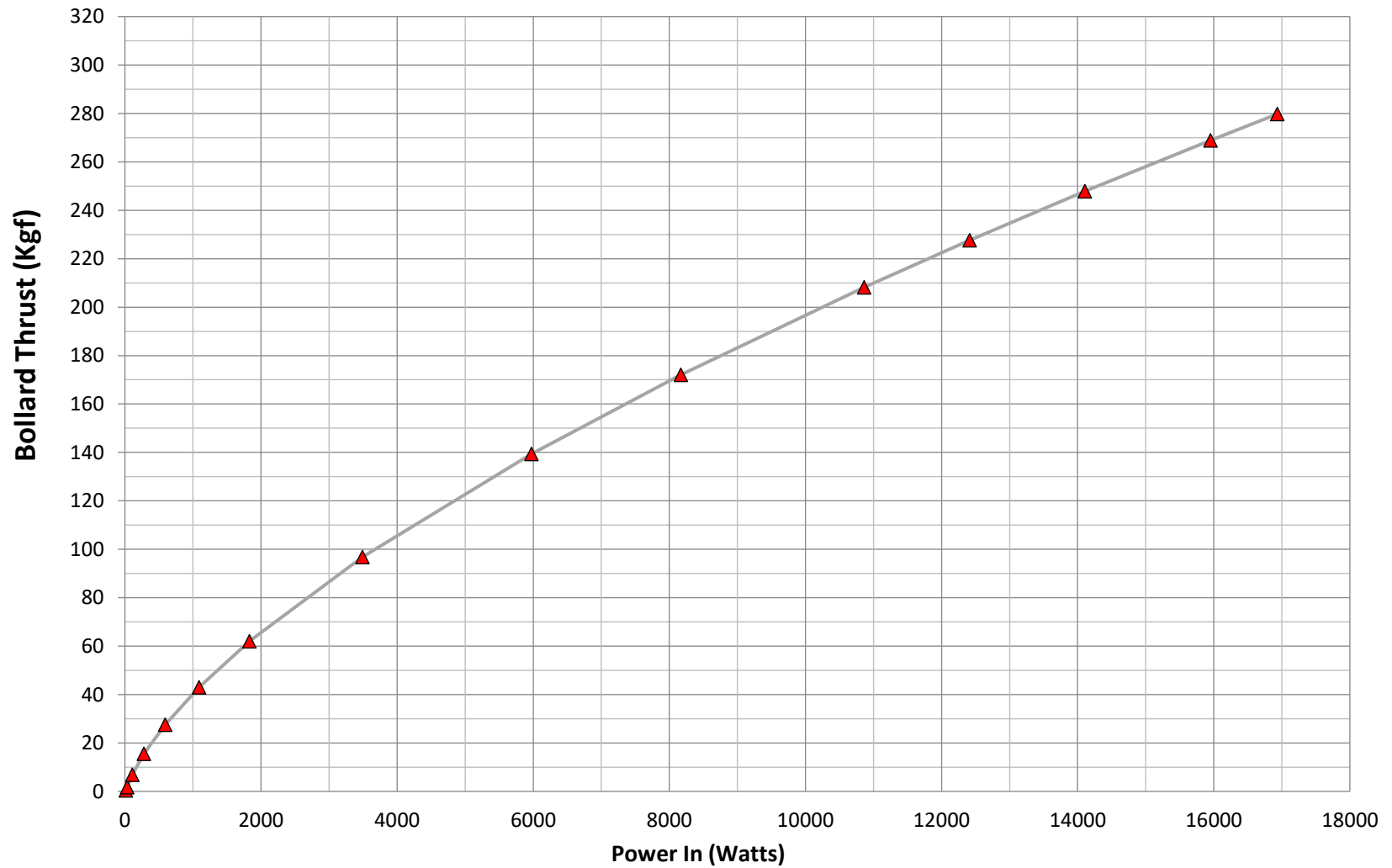
1002HL-14600XLR Hexscreen Electric Thruster Thrust (Lbf) vs Power In (HP)





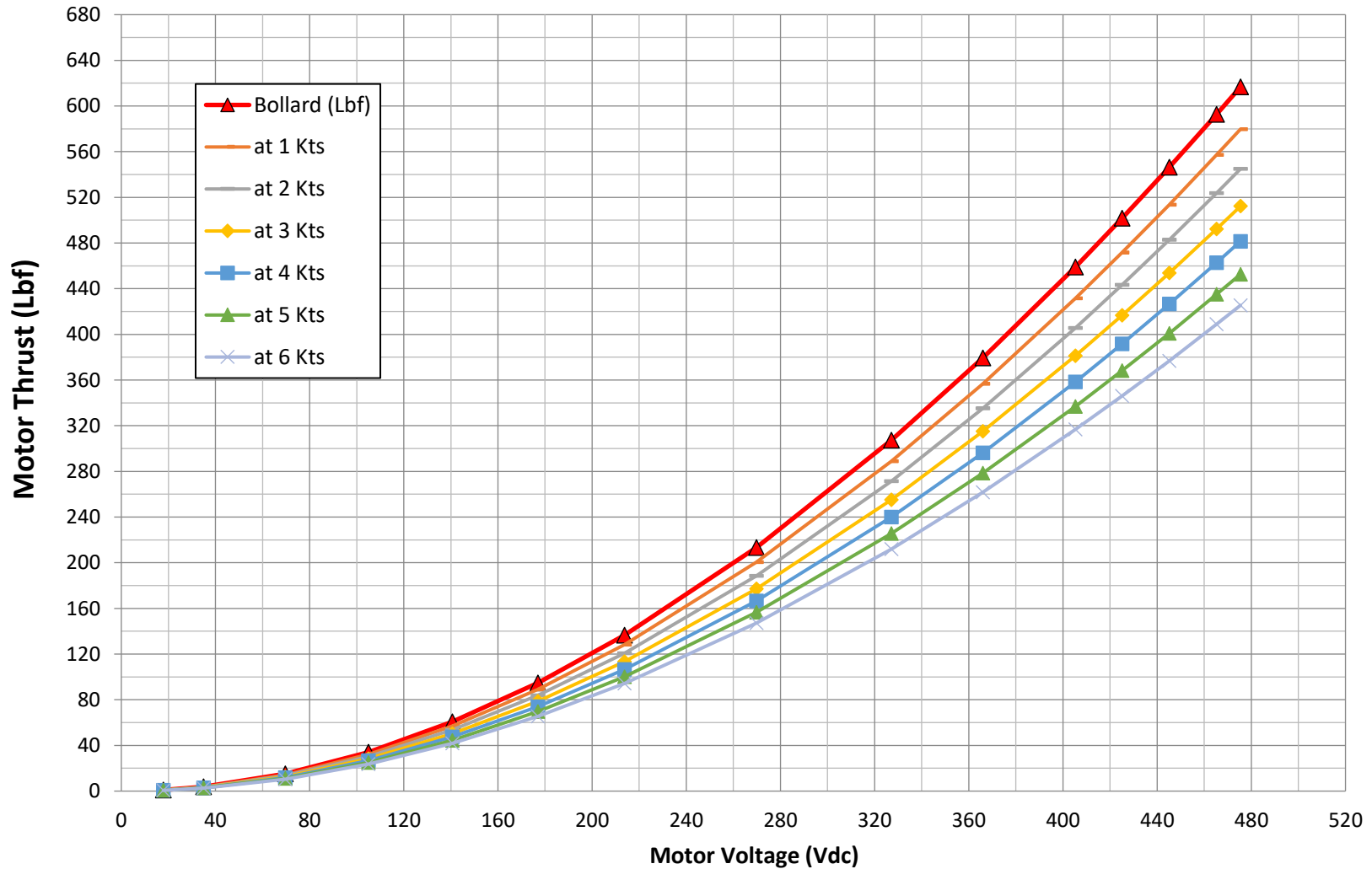
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1002HL-14600XLR Hexscreen Electric Thruster Thrust (Kgf) vs Power In (Watts)





1002HL-14600XLR Hexscreen Electric Thruster Thrust (Lbf) vs Voltage (Vdc)



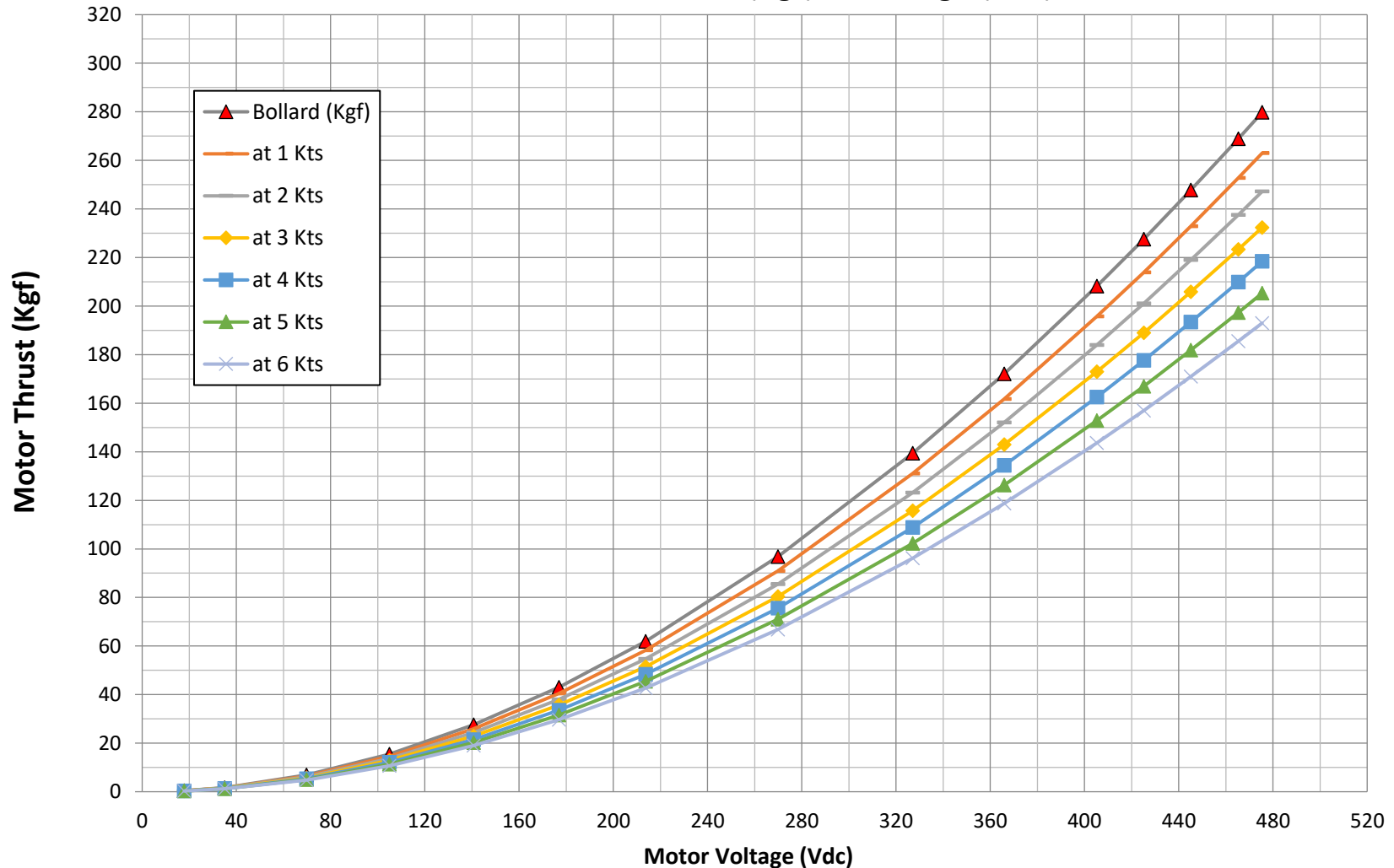
Note:

- 1) For Thrust at Forward Vehicle Speed (Kts), anything lower than 500 RPM varies greatly with vehicle design.
- 2) Thrust at forward vehicle speed from 1 Kts to 6 Kts is based on a local water speed with a very conservative vehicle wake factor.
- 3) System Voltage equals 600VDC. Graph shows Thrust with Voltages below 600VDC.



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1002HL-14600XLR Hexscreen Electric Thruster Thrust (Kgf) vs Voltage (Vdc)



Note:

- 1) For Thrust at Forward Vehicle Speed (Kts), anything lower than 500 RPM varies greatly with vehicle design.
- 2) Thrust at forward vehicle speed from 1 Kts to 6 Kts is based on a local water speed with a very conservative vehicle wake factor.
- 3) System Voltage equals 600VDC. Graph shows Thrust with Voltages below 600VDC.