



1002H Hexscreen Electric Thruster with 14150XLR Motor Performance Table

Speed (RPM)	System Voltage (VDC)	Min Voltage (VDC)	Current (A rms)	Torque (N-M)	Torque (In-Lbs)	Bollard Thrust 0 (Lbf)	Bollard Thrust 0 (Kgf)	Reverse Thrust (Lbf)	Reverse Thrust (Kgf)	Power Shaft (HP)	Power Shaft (Watts)	Power In (Watts)	Power In (HP)	Efficiency (Pout/Pin)
100	150	6.8	1.7	1.2	10.8	1	0.4	1	0.4	0.02	13	13	0.0	97.4%
200	150	13.4	2.1	1.5	13.2	4	1.7	3	1.6	0.04	31	32	0.0	98.4%
400	150	26.6	3.6	2.6	22.8	15	6.9	14	6.2	0.14	108	109	0.1	98.6%
800	150	53.7	9.6	6.9	61.1	61	27.5	55	25.0	0.78	579	590	0.8	98.1%
1000	150	67.5	14.0	10.2	89.9	95	43.0	86	39.0	1.43	1064	1088	1.5	97.8%
1200	150	81.4	19.5	14.1	125.0	137	62.0	124	56.1	2.38	1775	1822	2.4	97.5%
1300	150	88.4	22.7	16.4	145.0	160	72.7	145	65.9	2.99	2231	2293	3.1	97.3%
1400	150	95.5	26.0	18.8	166.5	186	84.3	168	76.4	3.70	2759	2842	3.8	97.1%
1500	150	102.6	29.7	21.4	189.7	213	96.8	193	87.7	4.51	3368	3474	4.7	96.9%
1600	150	109.8	33.5	24.2	214.4	243	110.1	220	99.8	5.44	4061	4197	5.6	96.8%
1700	150	117.0	37.6	27.2	240.8	274	124.3	248	112.7	6.49	4845	5017	6.7	96.6%
1800	150	124.3	42.0	30.4	268.7	307	139.4	279	126.3	7.68	5726	5940	8.0	96.4%
1900	150	131.6	46.6	33.7	298.3	342	155.3	310	140.8	8.99	6708	6972	9.3	96.2%
2000	150	138.9	51.5	37.2	329.4	379	172.1	344	156.0	10.45	7798	8120	10.9	96.0%
2100	150	146.3	56.6	40.9	362.2	418	189.7	379	171.9	12.07	9002	9391	12.6	95.9%

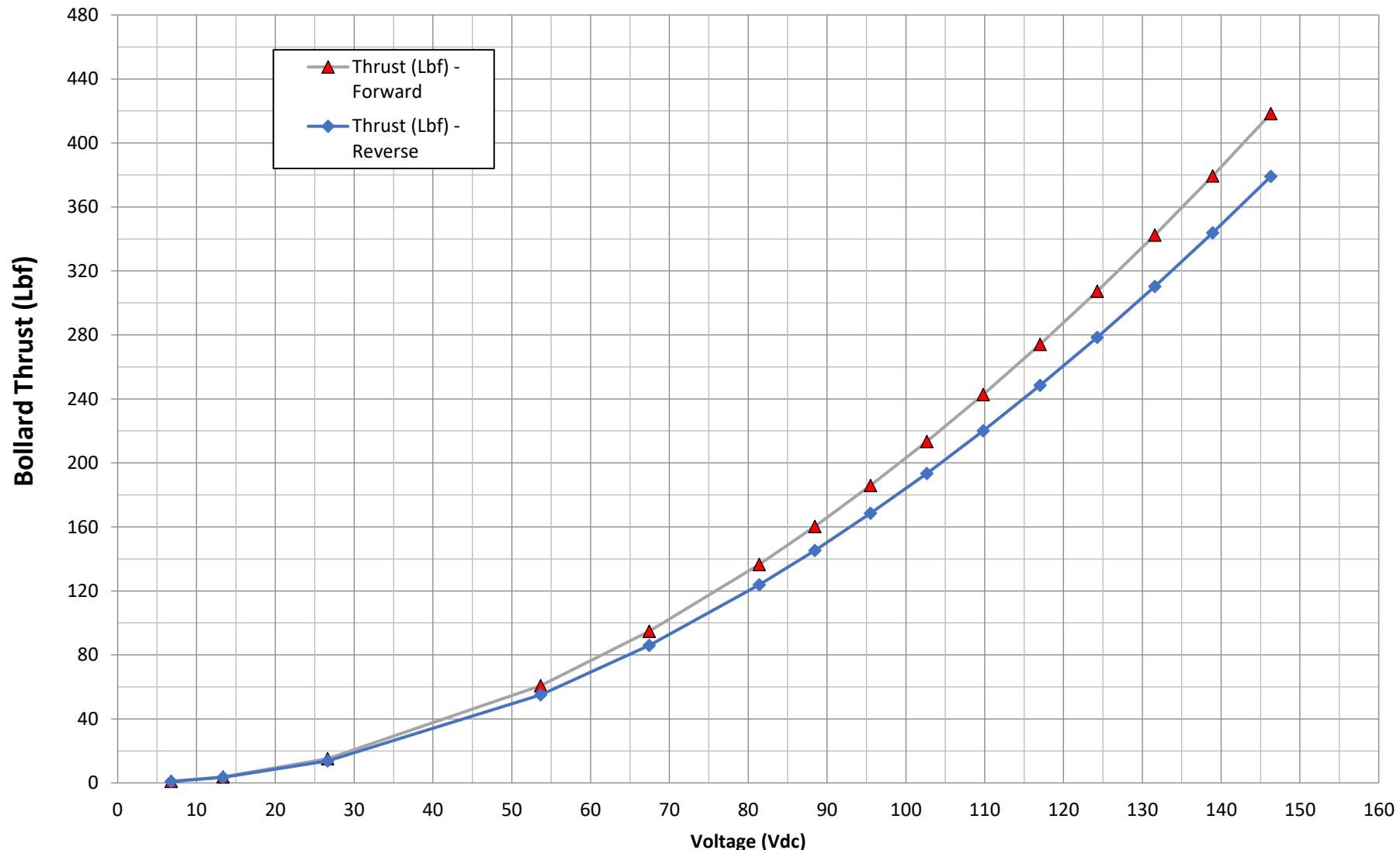
Table Information:

- 1) The Minimum Voltage column in the above table shows the minimum Voltage needed to achieve the performance at that corresponding propeller RPM/Thrust.
- 2) The Current shown represents the continuous RMS Current to the motor to achieve the Thrust at the corresponding propeller RPM.
- 3) The Shaft HP developed is a function of the propeller and increases with propeller RPM.
- 4) The maximum performance achieved will depend on the limitations of customers system Voltage and driver Current capacity.
- 5) For Thrust at Forward Vehicle Speed (Kts), anything lower than 500 RPM varies greatly with vehicle design.
- 6) The Current/RPM might need to be limited depending on customer connector spec and or system Current limitations.
- 7) Minimum Voltage to achieve full Thrust is 146 VDC.
- 8) Max Voltage should not exceed 10% of rated Voltage.



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1002H-14150XLR Hexscreen Electric Thruster Thrust (Lbf) vs Voltage (Vdc)



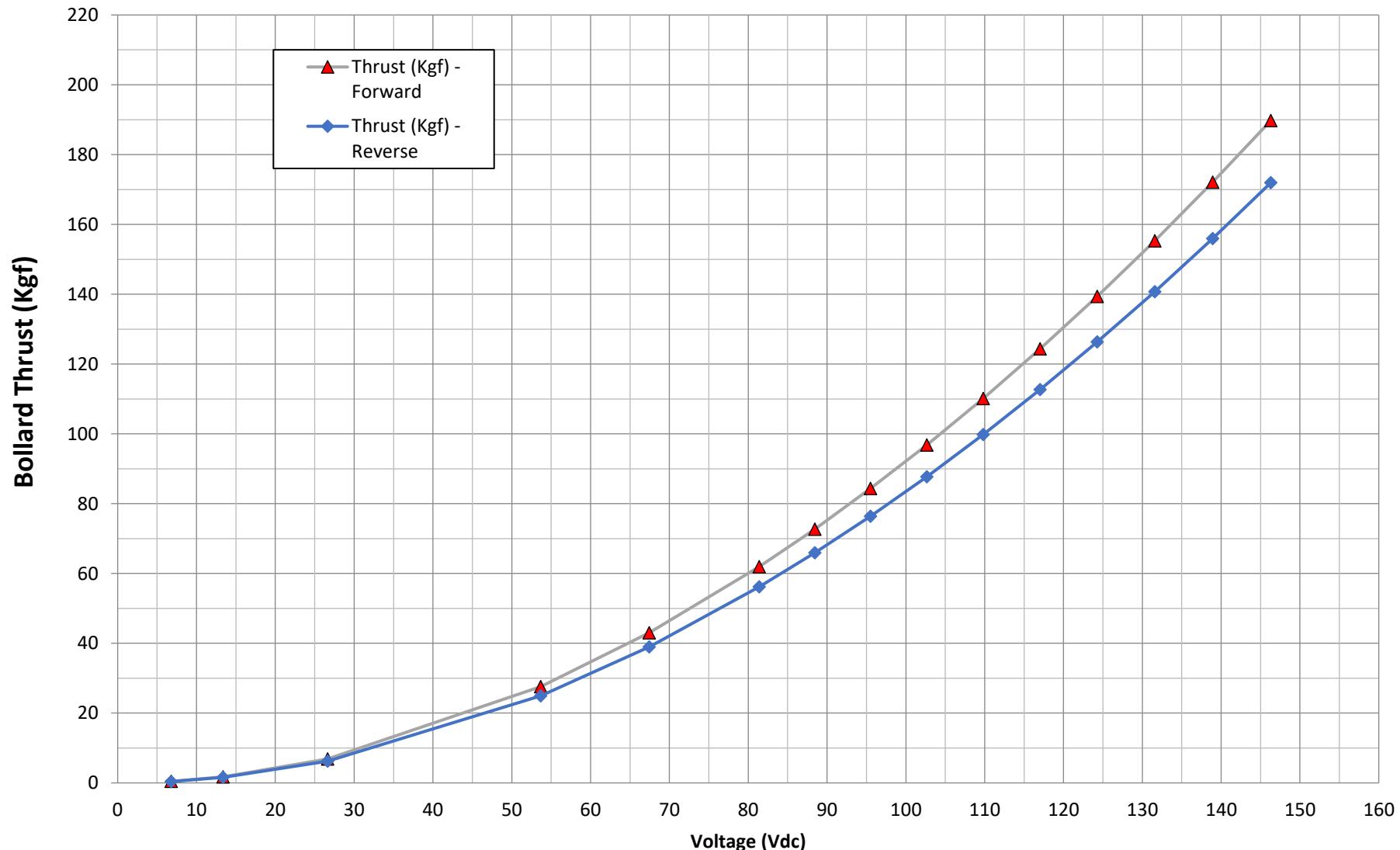
Note:

System Voltage equals 150VDC. Graph shows Thrust with Voltages below 150VDC.



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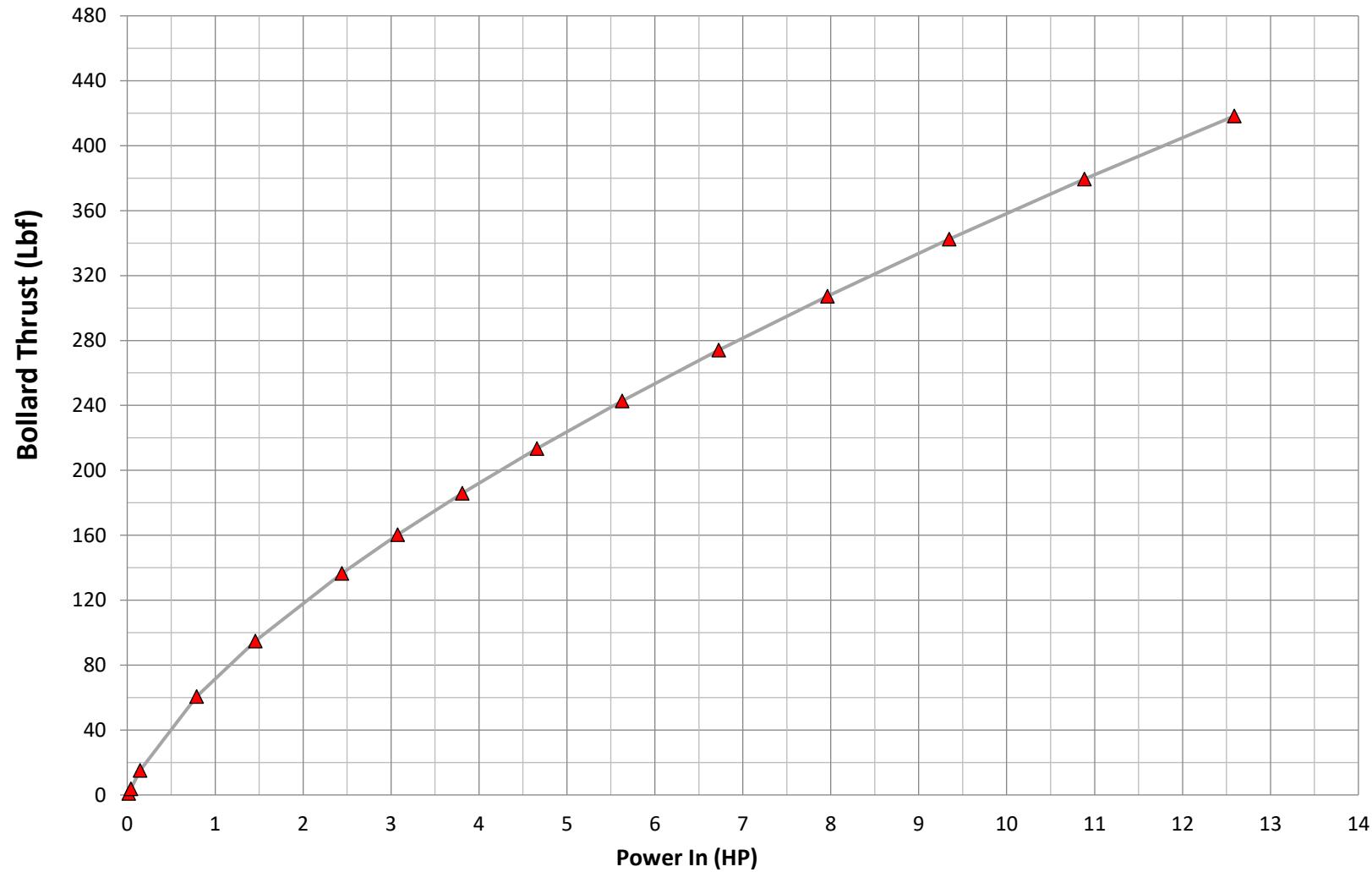
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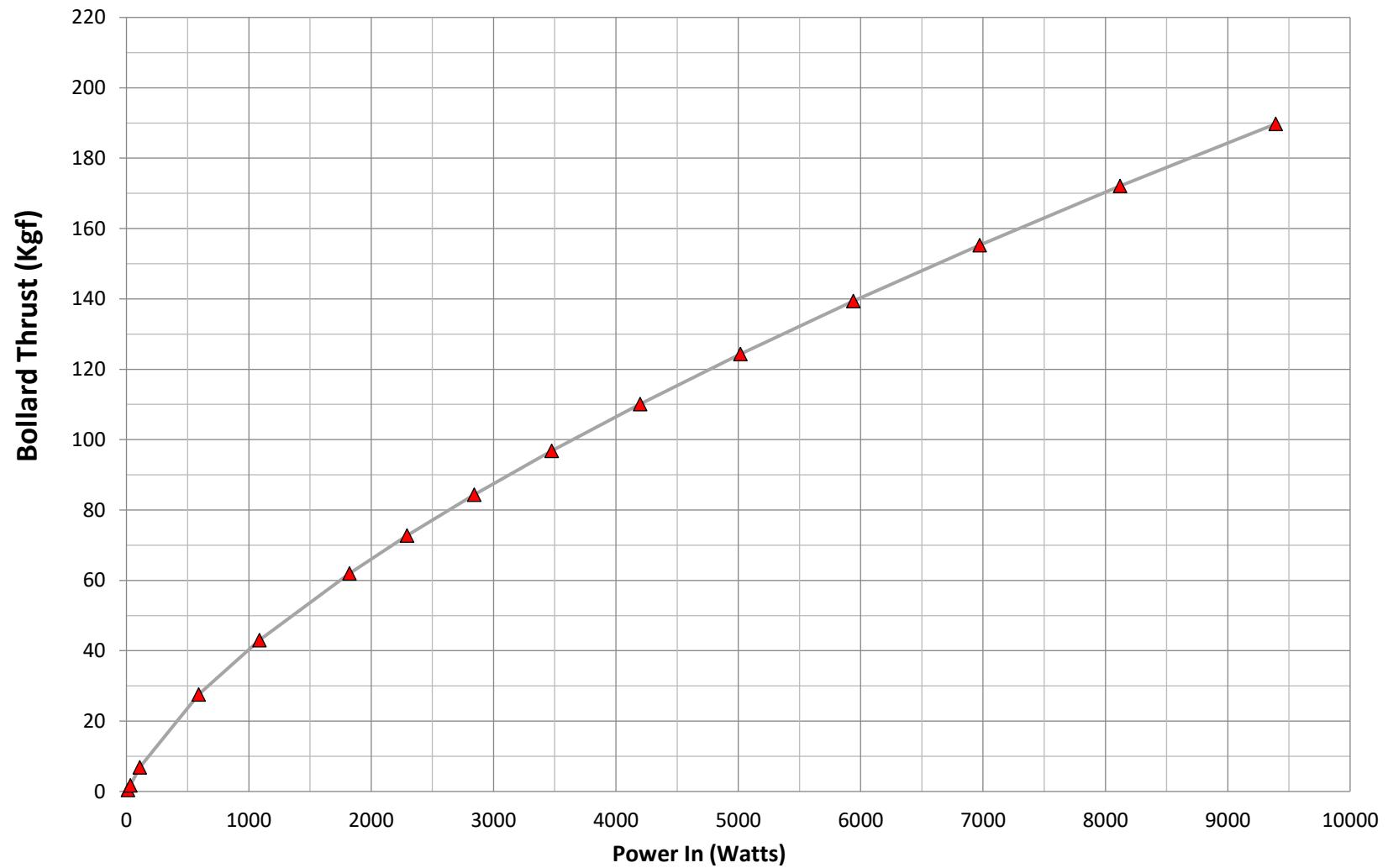
1002H-14150XLR Hexscreen Electric Thruster Thrust (Lbf) vs Power In (HP)





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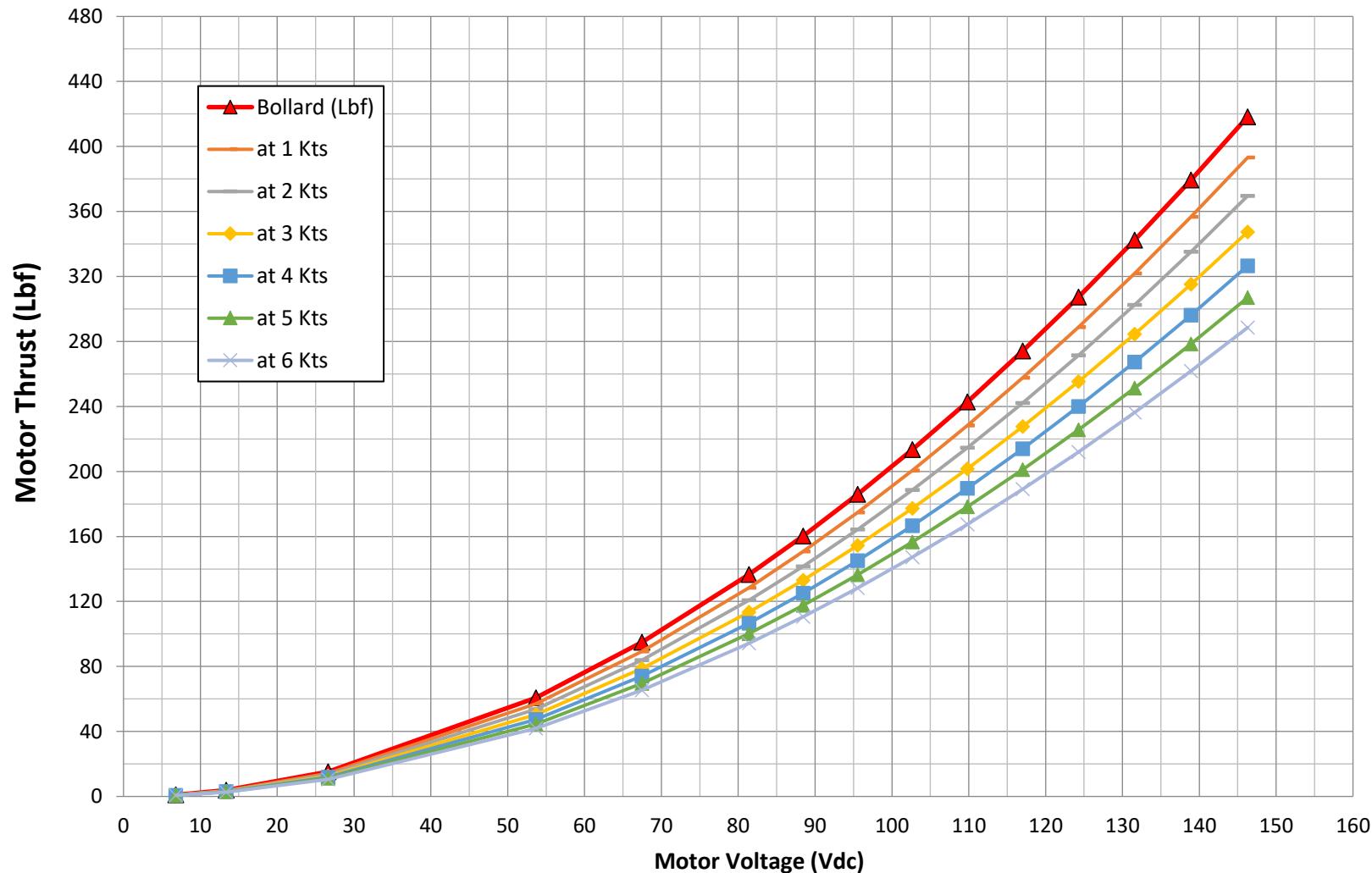
1002H-14150XLR Hexscreen Electric Thruster Thrust (Kgf) vs Power In (Watts)





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1002H-14150XLR Hexscreen Electric Thruster Thrust (Lbf) vs Voltage (Vdc)



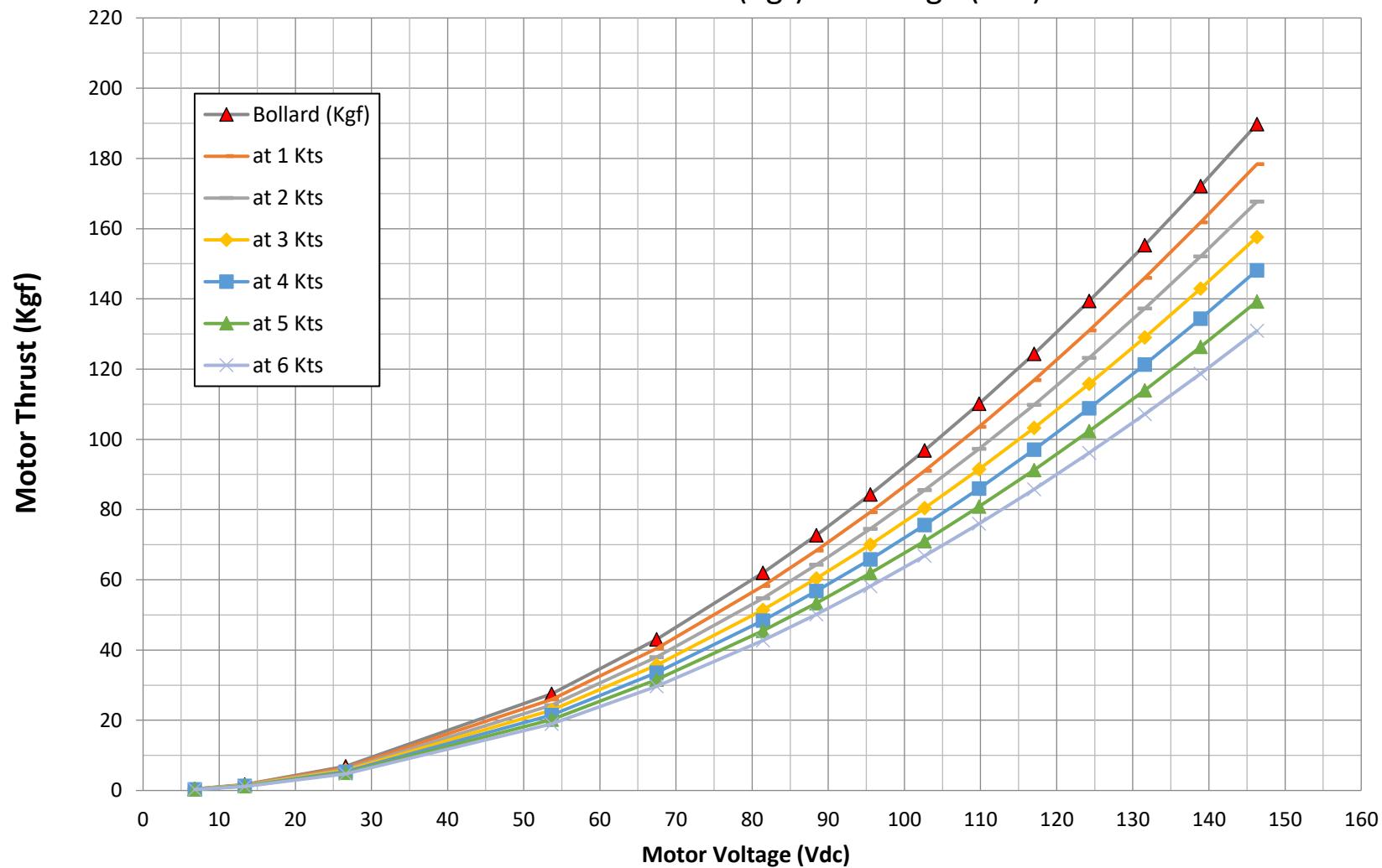
Note:

- 1) For Thrust at Forward Vehicle Speed (Kts), anything lower than 500 RPM varies greatly with vehicle design.
- 2) Thrust at forward vehicle speed from 1 Kts to 6 Kts is based on a local water speed with a very conservative vehicle wake factor.
- 3) System Voltage equals 150VDC. Graph shows Thrust with Voltages below 150VDC.



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1002H-14150XLR Hexscreen Electric Thruster Thrust (Kgf) vs Voltage (Vdc)



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